An Ice Storage Tank Modelica Model: Implementation and Validation

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Abstract

Energy storage systems have been gaining attention as a means of load management in grid-interactive efficient buildings. This study investigated the physics of the ice storage tank (IST) and implemented an IST model in Modelica. The developed IST Modelica model was compared with a similar model in EnergyPlus and was validated against experimental data from a testbed at the National Institute of Standards and Technology. Three statistical performance metrics were used to quantify the accuracy of the IST model. Validation results $(CV(RMSE) \le 10.20 \%, NMBE \le 0.44 \%)$ show that the proposed model has a good prediction accuracy according to ASHRAE Guideline 14.

Keywords: Ice storage tank, Modelica modeling, Model validation

1 Introduction

Ice thermal storage systems have been proven to be effective in reducing the cost of energy for operating buildings by shifting cooling demand from on-peak periods with high electricity prices to off-peak periods with lower electricity prices. The ice storage tank (IST) is a key component in an ice thermal storage system. By applying proper control strategies to the IST, research studies have shown significant cost savings including energy costs and demand reduction costs (e.g., 10 % to 55 %), which makes IST an attractive financial option for buildings (Braun 1990; Henze 2003; Candanedo 2013). Control-oriented modeling and simulation is an effective way to evaluate the system performance under different control strategies. Jekel (1991) created a model of a static ice-on-coil IST based on basic heat transfer relationships and analysis; the author used TRNSYS (Beckman 1994) to model a variable flow air-conditioner system connected with the IST. Both the charging and discharging periods of the tank operation were modeled and compared with manufacturers' data (Calmac ice tank model 1190 with working fluid of 25 % ethylene glycol). The prediction errors for the charging and discharging period were within 12 % and 10 % of the manufacturer's performance data, respectively. Ihm et al. (2004) developed an ice-based thermal storage model for EnergyPlus. This IST model uses the building load and system thermodynamic models for two direct ice systems (i.e. ice-on-coil external melt and ice harvester) and one indirect ice system (i.e. ice-oncoil internal melt). For the external (or internal) melt thermal storage tank, the brine flowing through coils charges and discharges the tank on the outside (or inside) of the coils. The thermal storage model systems were integrated as part of the EnergyPlus cooling plant components. Candanedo et al. (2013) numerically investigated the impact of different control strategies for a simplified ice storage system developed in EnergyPlus.

In terms of building energy and control system modeling, traditional building energy simulators, including TRNSYS and EnergyPlus, have the following limitations. First, these traditional simulation programs intertwine model equations and numerical solvers in their source code. The lack of separation between model equations, data, and solvers makes it hard for their models to support some use cases, especially when different control strategies and designs are involved (Wetter 2009). Second, some platforms, which are inherently designed for a steady-state simulation, are not suitable for evaluating the system dynamics, and the semantics of their control modules have little in common with how actual control works (Fu 2019). For example, EnergyPlus does not model local controllers (e.g., proportional-integral (PI) controller) for a building energy system. Additionally, the dead band and waiting time commonly used in building controls are not considered in EnergyPlus. The idealization of control makes it difficult to investigate, implement and verify actual control strategies in simulation (Wetter 2011; Fu 2018).

Certain commercial equipment, instruments, or materials are identified in this paper in order to specify the experimental procedure adequately. Such identification is not intended to imply recommendation or endorsement by NIST, nor is it intended to imply that the materials or equipment identified are necessarily the best available for the purpose.

To address these problems, the equation-based modeling language Modelica (Mattsson 1998) has been utilized to model and simulate building energy and control systems. The open-source Modelica Buildings Library (MBL) was developed by Lawrence Berkeley National Laboratory for typical building energy and control system modeling and simulation (Wetter 2014). However, the latest release of the MBL does not support the modeling of ice storage tank systems due to the lack of ice tank models.

This study implemented and validated an IST Modelica model based on MBL to support control-oriented studies, which could extend MBL to enable ice storage systems modeling and simulation. The rest of this paper is organized as follows: Section 2 describes the mathematical equations of the IST model and three statistical metrics to quantify and evaluate the model accuracy. Section 3 discusses how the IST model was implemented in the Modelica environment using the MBL. Section 4 validates the implemented IST model in Modelica against a similar model in EnergyPlus and experimental data from the National Institute of Standards and Technology (NIST). The final section is the conclusion.

2 Methodology

2.1 **IST Mathematical Model**

The mathematical model of the IST is based on the EnergyPlus model (Strand 1992) presented in Eqs. (1) to (8). The detailed IST model allows the users to model more closely specific manufacturers' ice storage units due to the use of curve fits. In section 4, the IST model was validated against an actual ice tank at NIST which is the type of ice-on-coil internal melt. The IST has three modes: a dormant mode when the storage is not engaged in operation, a discharging mode when the storage discharges cooling energy to the warm brine, and a charging mode when the storage is charged with the cold brine. When the tank is dormant, there is no fluid passing through the tank and the outlet temperature is considered to be equal to the inlet temperature. Details about the discharging mode and charging mode are shown.

Discharging Mode

$$\dot{q}^* \times \Delta t = d_1 + d_2(1 - P_{ch}) + d_3(1 - P_{ch})^2 + (1) [d_4 + d_5(1 - P_{ch}) + d_6(1 - P_{ch})^2] \Delta T_{lm}^*$$

$$\dot{q}^* = \frac{\dot{q}}{Q_{sto}} \tag{2}$$

$$\dot{q} = \dot{m}c_p(T_{out} - T_{in}) \tag{3}$$

$$\Delta T_{lm}^* = \frac{\Delta T_{lm}}{\Delta T_{nom}} \tag{4}$$

$$\Delta T_{lm} = \frac{\Delta T_1 - \Delta T_2}{\ln\left(\frac{\Delta T_1}{\Delta T_2}\right)} = \frac{T_{in} - T_{out}}{\ln\left(\frac{T_{in} - T_{fre}}{T_{out} - T_{fre}}\right)}$$
(5)

where, \dot{q}^* is the normalized instantaneous heat transfer rate between the brine and the ice in the tank; Δt is the time step of the operation data used in the curve fitting for discharging coefficients d_1 to d_6 ; P_{ch} is the fraction charged; ΔT_{lm} is the logarithmic mean temperature difference (LMTD); ΔT_{lm}^* is the LMTD between the inlet and outlet temperature of the tank normalized by a nominal temperature difference, ΔT_{nom} . Physically, \dot{q}^* is defined as the ratio of the instantaneous heat transfer rate \dot{q} to the total latent storage capacity Q_{sto} ; \dot{q} is negative when the tank is discharged. T_{in} is the tank inlet temperature, T_{out} is the tank outlet temperature, and T_{fre} is the freezing temperature of water or the latent energy storage material.

Eq. (5) is not numerically robust due to singularities that occur in the following scenarios: 1) $\Delta T_1 = \Delta T_2$, which causes a denominator of zero; 2) $\Delta T_1 = 0$ or $\Delta T_2 = 0$, which violates the logarithm function; 3) ΔT_1 and ΔT_2 have different signs. For a robust implementation of the Modelica LMTD calculation in the numerical environment, Eq. (5) is smoothed over different regions as shown in Eq. (5.1) to Eq. (5.5). The function $f_{smoothMax}(y, y_{lim})$ provides a continuously differentiable approximation for the variable y, which can be no less than the limiting value y_{lim} . The function $f_{smoothMin}(y, y_{lim})$ limits the variable y to be no larger than y_{lim} , where $\Delta y = y - y_{lim}$, and δ is used for regularization. When $|\Delta y| < \delta$, a second order polynomial function is used to create a smooth transition from y to y_{lim} . The smoothed functions not only help avoid the occurrence of zero in the denominator, but also ensure the continuity and differentiability of the simulated data.

$$\Delta T_1 = f_{smoothMax}(T_{in} - T_{fre}, T_{lim})$$
(5.1)

$$\Delta T_2 = f_{smoothMax}(T_{out} - T_{fre}, T_{lim})$$
(5.2)

$$\Delta T_{lm} = f_{smoothMin} \left(\frac{\Delta T_1 - \Delta T_2}{\ln\left(\frac{\Delta T_1}{\Delta T_2}\right)}, \Delta T_{lim} \right)$$
(5.3)

 $f_{smoothMax}(y, y_{lim})$

$$y_{lim}, \qquad (y < y_{lim} - \delta)$$

$$\frac{y + y_{lim}}{2}, \qquad (|\Delta y| = \delta) \qquad (5.4)$$

 $(v > v_{lim} + \delta)$

$$\begin{pmatrix} 4 \\ \end{pmatrix}$$

$$=\begin{cases} y_{lim}, & (y > y_{lim} + \delta) \\ y, & (y < y_{lim} - \delta) \\ \frac{y + y_{lim}}{2}, & (|\Delta y| = \delta) \\ \frac{\Delta y^{2}}{\delta} \left(\frac{\Delta y^{2}}{\delta^{2}} - 3\right) \\ \frac{4}{4} + \frac{y + y_{lim}}{2}, (|\Delta y| < \delta) \end{cases}$$
(5.5)

When the thermal tank is being charged, the charging heat transfer is calculated by Eq. (6). The constant parameters $c_1 \sim c_6$ are charging coefficients.

$$\dot{q}^{*} \times \Delta t = c_{1} + c_{2}P_{ch} + c_{3}P_{ch}^{2} + [c_{4} + c_{5}P_{ch} + c_{6}P_{ch}^{2}]\Delta T_{lm}^{*}$$
(6)

For both discharging mode and charging mode, the mass of ice in the tank is calculated by Eqs. (7) and (8), where *SOC* is the state of charge that indicates the mass ratio (0 %-100 %) of ice in the tank, *SOC'* is the derivative of *SOC*, H_f is the latent heat of fusion for water at 0 °C, m_{ice} is the mass of ice in the tank, $m_{ice,max}$ is the maximum ice capacity of the tank, and \dot{m} is the mass flow rate of the fluid.

$$SOC' = \frac{\dot{m}c_p(T_{out} - T_{in})}{m_{ice,max}H_f}$$
(7)

$$SOC = \frac{m_{ice}}{m_{ice,max}} \tag{8}$$

2.2 Validation Metrics

To evaluate the accuracy of the proposed model, three statistical metrics are applied: Coefficient of Variation of Root Mean Square Error (CV(RMSE)), the coefficient of determination (R^2), and the Normalized Mean Bias Error (NMBE). These metrics are defined in Eq. (9) to Eq. (12).

$$RMSE = \sqrt{\frac{\sum_{i=1}^{n} (Y_i - \hat{Y}_i)^2}{n}},$$
(9)

$$CV(RMSE) = \frac{RMSE}{\bar{Y}_i},\tag{10}$$

$$R^{2} = 1 - \frac{\sum_{i=1}^{n} (Y_{i} - \hat{Y}_{i})^{2}}{\sum_{i=1}^{n} (Y_{i} - \bar{Y}_{i})^{2}},$$
(11)

$$NMBE = \frac{\sum_{i=1}^{n} (Y_i - \hat{Y}_i)^2}{(n-p) \times \bar{Y}_i},$$
 (12)

where, Y_i is the measured data, \hat{Y}_i is the predicted data, n is the number of data points, \bar{Y}_i is the mean value of the measured data, p is the number of parameters in the numerical model.

According to ASHRAE Guideline 14 (ASHRAE 2014), the predicted model shall have an NMBE up to 5 % and a CV(RMSE) up to 15 % using monthly calibration data. If hourly calibration data are used, these requirements shall be 10 % and 30 %, respectively.

3 Modelica Modeling

3.1 Model Description

The IST Modelica model contains four key components as presented in Figure 1: LMTD calculator, heat flow rate calculator, storage mode selector, and outlet temperature controller. The storage mode selector sends the mode

signal (discharging, charging, dormant) to the LMTD calculator and the outlet temperature controller that controls the outlet temperature to the setpoint. The heat flow rate calculator outputs the SOC and ice mass. Table 1 summarizes the key components in the IST Modelica model.

Table 1. Description of the IST Modelica model.				
Components	Model Description			
LMTD Calculator	LMTD algorithm with <i>smooth</i> functions			
Heat Flow Rate	Polynomial coefficients of			
Calculator	curve fitting data			
Storage Mode	Discharging, charging,			
selector	dormant mode			
Outlet Temp	PI control for the main valve			
Controller	and bypass valve			



Figure 1. Schematic diagram of the IST model.



Figure 2. Modelica model of the ice storage tank.

3.2 Model Components

Figure 2 presents the detailed components inside the IST Modelica model; details of each component are described below.

LMTD Calculator

LMTD is the key intermediate variable that determines the calculation process of the whole model, which is calculated by Eqs. (5.1) - (5.5).

Heat Flow Rate Calculator

The heat flow rate is calculated by Eq. (1) and Eq. (6) for discharging and charging mode, respectively. When the tank is dormant, the heat flow rate is assumed to be zero.

Storage Mode Selector

The storage mode selector determines the operating mode of the tank (i.e., dormant, discharging, or charging modes) in response to measured system states such as SOC, the flow rate, and the inlet temperature of the coolant.

The state diagram of the storage mode selector is shown in Figure 3. If the mass flow rate is greater than the minimum flow rate, the inlet temperature is greater than the freezing temperature of water plus a temperature tolerance ($dT_{if,min}$), and SOC is greater than a discharging tolerance, then the ice storage tank is in the discharging mode. If the mass flow rate is greater than the minimum flow rate, the inlet temperature is less than the freezing temperature of water minus a temperature tolerance, and SOC is less than a charging tolerance, then the ice storage tank is in the charging mode. Otherwise, the tank is dormant and bypassed. Figure 4 shows the state graph diagram implemented in Modelica, which has four input signals and one output signal, the storage mode.



Figure 3. State diagram of the storage mode selector.



Figure 4. Modelica diagram of the storage mode selector.

• Outlet Temperature Controller

The IST outlet temperature is maintained at its setpoint by adjusting the bypass valve position through a built-in PI controller. The control values and diagram of the outlet temperature controller are shown in Table 2 and Figure 5, where K1 is the opening value of the main valve, K2 is the opening value of the bypass valve, and u_{PI} is the output value of a built-in PI controller. If the tank is dormant, the main valve will be closed (K1=0) and the bypass valve will be fully open (K2=1). If the tank is charged, the main valve will be fully open (K1=1) and the bypass valve will be closed (K2=0). If the tank is discharged, the PI controller will adjust the main valve and the bypass valve to meet the outlet temperature setpoint (K1=1- u_{PI} , K2= u_{PI}).

Table 2. Control values of the outlet temperature controller.

Mode	Dormant	Charging	Discharging
Main	Off	On	On
Valve	(K1 = 0)	(K1 = 1)	$(\mathbf{K}1=1\boldsymbol{-}\boldsymbol{u}_{PI})$
Bypass	On	Off	On
Valve	(K2 = 1)	(K2 = 0)	$(K2 = u_{PI})$



Figure 5. Modelica diagram of the outlet temperature controller.

4 Comparison and Validation

This section presents the comparison and validation of the IST Modelica model against two data sources: 1) a similar model in EnergyPlus and 2) measurement data from NIST. Three accuracy metrics are presented.

4.1 Modelica Model vs. EnergyPlus Model

We selected a built-in IST model in an EnergyPlus ice tank example file that is based on the same mathematical model (Strand 1992) presented in Eqs. (1) to (8). Table 3 lists the details of the EnergyPlus model with modified parameters (cooling capacity, polynomial coefficients of charging curve data, and medium type). The IST EnergyPlus model was simulated for about 8 hours (from 10 a.m. to 6 p.m.) of discharging operation and 2 hours (from 0 a.m. to 2 a.m.) of charging operation on July 21st using typical meteorological year (TMY3) weather data. Then the simulated dataset (inlet/outlet temperature of IST, mass flow rate of chilled water, and SOC) from EnergyPlus was exported for use in the Modelica virtual testcase.

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Descriptions	EnergyPlus model
Filename	5ZoneDetailedIceStorage. idf
Weather Data	Chicago-Midway AP 725340 (TMY3)
Floor Area	463.6 m ²
Ice Storage Capacity	0.05 GJ
Number of Story	1
Number of Zones	6
Timestep of Simulation	1 min
Discharging Curve	d = [0.0, 0.09, -0.15, 0.612, -0.324, -0.216]
Discharging Time	10 a.m. to 6 p.m., July 21st
Charging Curve	c = [0.318, 0, 0, 0, 0, 0]
Charging Time	12a.m. to 2a.m., July 21 st
Medium	30 %PG (propylene
	glycol) + 70 %Water

A virtual testcase was built for the IST Modelica model as presented in Figure 6. The Modelica virtual testcase uses the same IST parameters and inlet conditions (mass flow rate, temperature, etc.) as in EnergyPlus, and compares the tank states (e.g., SOC) and the calculated outlet conditions (e.g., outlet temperature) with those in EnergyPlus. Figure 7 shows the comparison results for SOC and outlet temperature in discharging mode. Figure 8 shows the comparison results in charging mode. The comparisons indicate that the simulated SOC and outlet temperature of the IST Modelica model are in excellent agreement with the outputs of the IST EnergyPlus model.



Figure 6. Virtual testcase for the IST Modelica model.

Three statistical metrics (CV(RMSE), NMBE, and R^2) were calculated to evaluate the accuracy of the prediction, and the results are shown in Table 5. R^2 ranges from 0.9311 to 0.9999, CV(RMSE) ranges from 0.00 % to 0.55 %, and NMBE is 0.00 % in all scenarios. All three metrics show excellent agreement between the tank performance predictions from the IST Modelica model and the IST EnergyPlus model, which is not a surprise since these two models use the same mathematical equations, though our IST model has more detailed local controls.

4.2 Simulated Data vs. Measured Data

In this section, we validate the model prediction with the experimental data obtained from an ice tank testbed at NIST (Pertzborn 2016, Pradhan 2020). Per the manufacturer, the ice storage tank at NIST contains 3,105 L of water and when fully frozen the ice has a capacity of 274 kWh, designed to be discharged over an eight-hour period with an inlet temperature of 10 °C. The chilled water that flows through the IST is a 30 % PG and 70 % water solution, and the heat exchanger inside the IST is a spiral wound polyethylene tube. The data was collected at a 0.10 Hz rate. The measured temperature and flow rate of the chilled water are used as the boundary conditions in the Modelica virtual testcase. Table 4 shows the polynomial coefficients for discharging mode and charging mode, which are obtained by regression of the measured data.

Coefficients	d_1/c_1	d_{2}/c_{2}	d_3/c_3	d_4/c_4	d_{5}/c_{5}	d_6/c_6	
Discharging	5.54E-5	-1.46E-4	9.28E-5	1.12E-3	-1.10E-3	3.01E-4	
Charging	2.00E-4	0	0	0	0	0	

Mode	SOC			Outlet Temperature		
moue	CV(RMSE)	R^2	NMBE	CV(RMSE)	R^2	NMBE
Discharging	0.35 %	0.9999	0.00 %	0.00 %	0.9999	0.00 %
Charging	0.55 %	0.9986	0.00 %	0.04 %	0.9311	0.00 %

Table 5. Results of statistical metrics (Benchmark: EnergyPlus).



Figure 7. Discharging results comparison of the Modelica model with the EnergyPlus model.





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Mode &	SOC			Outlet Temperature		
Date	CV(RMSE)	R^2	NMBE	CV(RMSE)	R^2	NMBE
Discharging (5/14/2018)	7.09 %	0.9778	0.27 %	0.27 %	0.8281	0.21 %
Charging (5/16/2018)	10.20 %	0.9810	0.44 %	0.10 %	0.8344	0.03 %

Table 6. Results of statistical metrics (Benchmark: measured data from NIST).









For the discharging mode, the Modelica model is validated using the experimental data on 5/14/2018. For the charging mode, the Modelica model is validated using the experimental data on 5/16/2018. Figure 9 and Figure 10 show the comparison of simulated results with measured data of the SOC and outlet temperature for two days, respectively.

Table 6 shows the results of three accuracy metrics (CV(RMSE), NMBE, and R²). The R² (0.8281 - 0.9810) values are high enough to indicate good agreement between the predictions and the measurement data. ASHRAE Guideline 14 suggests that the predicted model shall have a CV(RMSE) up to 30 % and an NMBE up to 10 % using hourly calibration data (ASHRAE 2014). Comparing the IST Modelica model with the experimental data from NIST, the results of CV(RMSE) (0.10 % - 10.20 %) and NMBE (0.03 % - 0.44 %) indicate that the IST Modelica model can provide good accuracy according to ASHRAE Guideline 14.

5 Conclusion

This study implemented an ice storage tank model based on the Modelica Buildings Library. The model was then compared to and validated against the EnergyPlus model and the measured data from a real ice tank system, respectively. The validation results quantified by three statistical metrics show a good prediction accuracy. In the future, the proposed IST Modelica model will be tested on system-level control evaluations and be used for load side management for better building-to-grid integration.

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Nomenclature

Abbreviations:

ASHRAE: American Society of Heating, Refrigerating and Air-Conditioning Engineers CV(RMSE): Coefficient of Variation of Root Mean Square Error IST: Ice Storage Tank LMTD: Logarithmic Mean Temperature Difference MBL: Modelica Buildings Library NIST: National Institute of Standards and Technology NMBE: Normalized Mean Bias Error PG: Propylene Glycol PI : Proportional-Integral SOC: State of Charge *Symbols:* c_i : Charging coefficients d_i : Discharging coefficients

 H_f : Latent heat of fusion for water at 0 °C

m: Mass flow rate of liquid

 m_{ice} : Ice mass in the tank

 P_{ch} : Charged fraction

 \dot{q} : Instantaneous heat transfer rate

 \dot{q}^* : Normalized instantaneous heat transfer rate

 Q_{sto} : Total latent storage capacity

 T_{in} : Tank inlet temperature

 T_{out} : Tank outlet temperature

 T_{fre} : Freezing temperature of the water

 Δt : Timestep of the operation data used in the curve fitting ΔT_{lm} : LMTD

 ΔT_{lm}^* : Normalized LMTD

 ΔT_{nom} : Nominal temperature difference

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